

User's
Manual

**Model UT130
Temperature Controller**



IM 05C01E02-41E

Note: This user's manual (IM 05C01E02-41E) is a re-edited, A4-size version of the IM 05C01E02-01E user's manual that is supplied along with the product shipped. Therefore, both manuals have the same contents, except for some minor differences in the cross-referenced page numbers.

Revision Record

- Manual No. : IM 05C01E02-41E(2nd Edition)
- Title : Model UT130 Temperature Controller

| Edition | Date | Revised Item |
|---------|-----------|-----------------|
| First | Nov.,2000 | Newly published |
| Second | Mar.,2001 | Correct |

Please read through this user's manual to ensure correct usage of the controller and keep it handy for quick reference.

CONTENTS

| | |
|---|-----------|
| 1. Notice | 2 |
| 2. What is on the Front Panel? | 3 |
| 3. Installing the Controller | 4 |
| 4. Panel Cutout Dimensions and External Dimensions | 5 |
| 5. Wiring | 6 |
| 6. Hardware Specifications | 8 |
| 7. Key Operations | 9 |
| 8. Troubleshooting | 18 |

■ Checking Package Contents

Before using the product, check that its model & suffix codes are as you ordered.

Model and Suffix Codes

| Model | Suffix code | Description |
|---|--|---|
| UT130 | | Temperature controller |
| Control output for standard type (or for heating) | -R -V | Relay output (time-proportional PID or on/off control) Voltage pulse output (time-proportional PID) |
| Control output for cooling | N R V | No cooling output (standard type) Relay output (time-proportional PID or on/off control) Voltage pulse output (time-proportional PID) |
| Option | /AL /HBA /RS /V24 | Alarm outputs (2 points) Heater disconnection alarm (includes optional /AL function) Communication function Power Supply 24V DC / 24V AC |

Note: When specifying the /RS option, be sure to order the required number of copies of Communication Functions User's Manual separately.

Check the package contents against the list below.

- Temperature controller 1
- Mounting bracket 1
- User's manual (IM 05C01E02-01E) 1

1. NOTICE

The following safety symbol is used both on the product and in this user's manual.



This symbol stands for "Handle with Care." When displayed on the product, the operator should refer to the corresponding explanation given in the user's manual in order to avoid injury or death of personnel and/or damage to the product. In the manual the symbol is accompanied by an explanation of the special care that is required to avoid shock or other dangers that may result in injury or loss of life.

The following symbols are used in this manual only.



NOTE

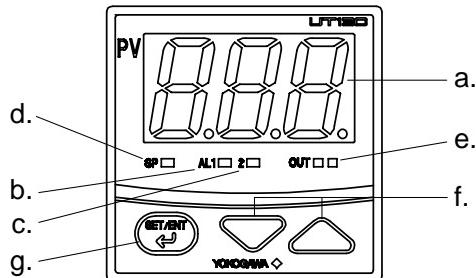
Indicates that operating the hardware or software in a particular manner may lead to damage or result in system failure.



IMPORTANT

Draws attention to information that is essential for understanding the operation and/or features of the product.

2. WHAT IS ON THE FRONT PANEL?



| | Name | Function |
|----|--|--|
| a. | Data display (red) | <ul style="list-style-type: none"> In the operating display, either PV (measured value) or SP (target setpoint) is indicated. Which parameter takes precedence over the other depends on the DSP parameter value. In the parameter setting display, either the parameter codes or parameter value is indicated. If an error occurs, the error code is displayed. |
| b. | Alarm 1 (AL1) lamp (red) | Lit when alarm 1 is activated. |
| c. | Alarm 2 (AL2) lamp (red) | Lit when alarm 2 is activated. |
| d. | SP display lamp (orange) | <ul style="list-style-type: none"> Lit when the SP is displayed or being changed. Flashes slowly (approx. once every second) when a parameter code is displayed. Flashes fast when a parameter value is being changed. |
| e. | Output (OUT) display lamps (Left: orange; right: green) | <ul style="list-style-type: none"> Lit while control output is being output. The left lamp is lit in orange during control output of standard type. In heating/cooling type, the left lamp lights up in orange when the heating-side output is active; while the right lamp lights up in green when the cooling-side output is active. |
| f. | Data change keys (Indicated as simply the ▲ and ▼ keys hereafter.) | <ul style="list-style-type: none"> When PV is displayed on the operating display, a press of the ▲ or ▼ key switches to the SP display. When a parameter code is displayed, pressing either key once displays the parameter value (which can then be changed). Changes SP and the parameter values. Pressing the ▲ key decreases the data value and pressing the ▼ key increases it. Holding down the key will gradually increase the speed of the change. |
| g. | SET/ENT key (data registering key) (Indicated as simply the SET key hereafter.) | <ul style="list-style-type: none"> On the operating display, it switches between the PV and SP displays. Registers the data value changed using the data change keys. Switches between operating displays or parameter setting displays sequentially. Pressing the key for 3 seconds or longer in the operating display retrieves the operating parameter setting display. Pressing the key for 3 seconds or longer in either an operating or setup parameter setting display transfers back to the operating display. (See Page 12.) |

3. INSTALLING THE CONTROLLER



CAUTION

To prevent electric shock, the source of power to the controller must be turned off when mounting the controller on to a panel.



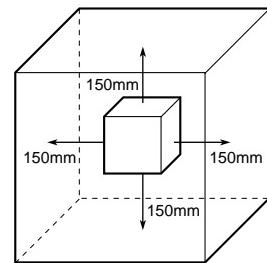
NOTE

To install the controller, select a location where:

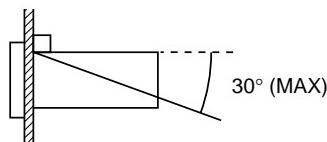
1. No-one may accidentally touch the terminals;
2. Mechanical vibrations are minimal;
3. Corrosive gas is minimal;
4. The temperature can be maintained at about 23°C with minimal fluctuation;
5. There is no direct heat radiation;
6. There are no resulting magnetic disturbances;
7. The terminal board (reference junction compensation element, etc.) is protected from wind;
8. There is no splashing of water; and
9. There are no flammable materials.

Never place the controller directly on flammable items.

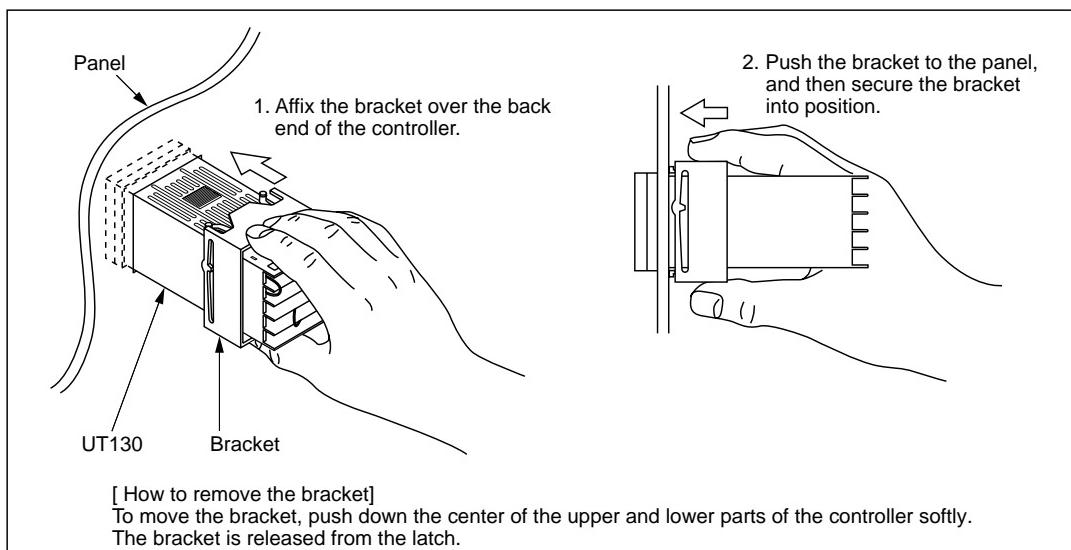
If the controller has to be installed close to flammable items or equipment, be sure to enclose the controller in shielding panels positioned at least 150mm away from each side. These panels should be made of either 1.43mm thick metal-plated steel plates or 1.6mm thick uncoated steel plates.



● Mount the controller at an angle within 30° from horizontal with the screen facing upward. Do not mount it facing downward.

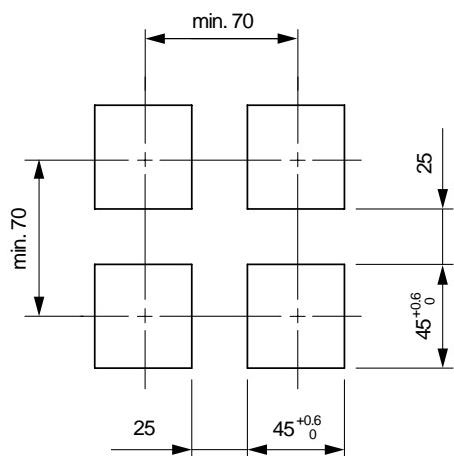


■ Mounting the Controller



4. PANEL CUTOUT DIMENSIONS AND EXTERNAL DIMENSIONS

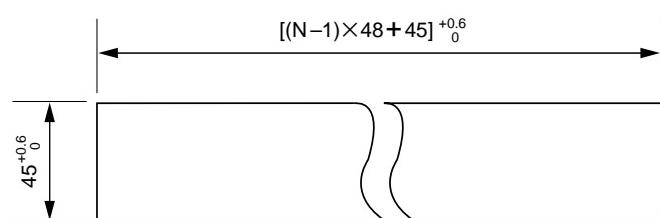
1. General Mounting



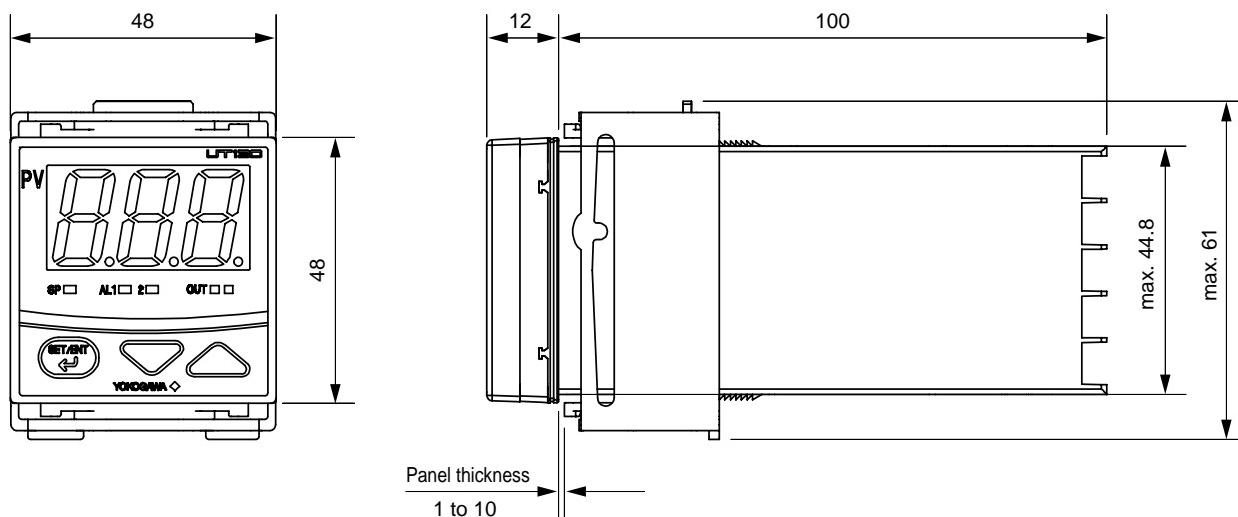
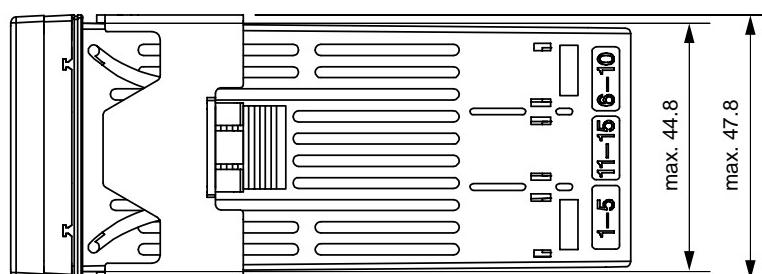
2. Side-by-side Close Mounting

(Splash-proof construction is unavailable)

Unit: mm



N is the number of controllers.
If N≥5, then measure the actual length.



5. WIRING



CAUTION

- 1) Before you start wiring, turn off the power source and use a tester to check that the controller and cables are not receiving any power in order to prevent electric shock.
 - 2) Wiring should be carried out by personnel with appropriate electrical knowledge and experience.
-



NOTE

- 1) Use a single-phase power source. If the source has a lot of noise, use an isolation transformer for the primary side and a line filter (we recommend TDK's ZAC2205-00U product) for the secondary side. When this noise-prevention measure is taken, keep the primary and secondary power cables well apart. Since the controller has no fuse, be sure to install a circuit breaker switch (of 5A and 100V AC or 220V AC, and that conforms to IEC standards) and clearly indicate that the device is used to de-energize the controller.
 - 2) For thermocouple input, use shielded compensating lead wires. For RTD input, use shielded wires which have low resistance and no resistance difference between the 3 wires. See the table given later for the specifications of the cables and terminals and the recommended products.
 - 3) The control output relay cannot be replaced even though it has a limited service life (100,000 relay contacts for the resistance load). Thus, an auxiliary relay should be used so that the load can be turned on and off.
 - 4) When using an inductive load (L) such as an auxiliary relay and solenoid valve, be sure to insert a CR filter (for AC) or diode (for DC) in parallel as a spark-rejecting surge suppressor to prevent malfunctions or damage to the relay.
 - 5) When there is the possibility of being struck by external lightning surge, use the arrester to protect the instrument.
-



IMPORTANT

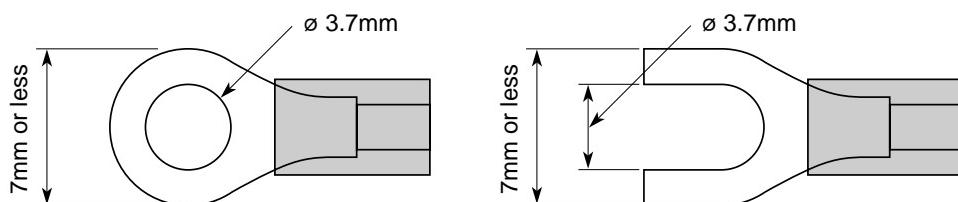
Always fix a terminal cover bracket to the UT130 controller before wiring if an optional anti-electric-shock terminal cover (part number: L4000FB) is used.

● Cable Specifications and Recommended Products

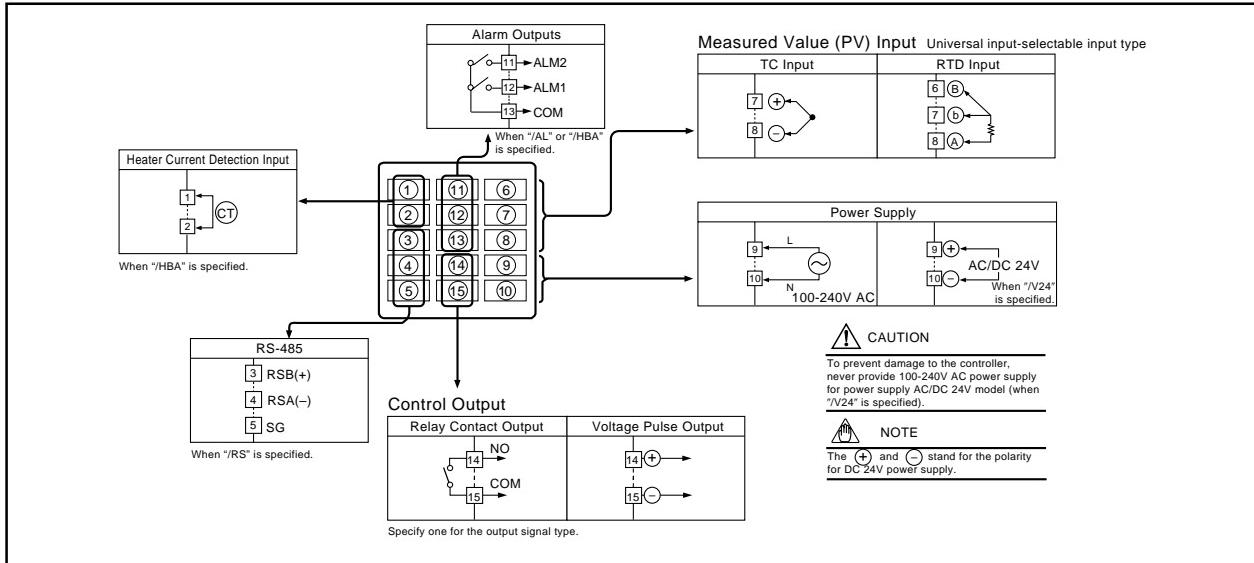
| | |
|---------------------------------------|---|
| Power supply and relay contact output | 600V vinyl insulated wire/cable, JIS C3307, 0.9 to 2.0mm ² |
| Thermocouple input | Shielded compensating lead wire, JIS C1610 |
| RTD input | Shielded wire (3-wire), UL2482 (Hitachi cable) |
| Other signals | Shielded wire |

● Recommended Terminals

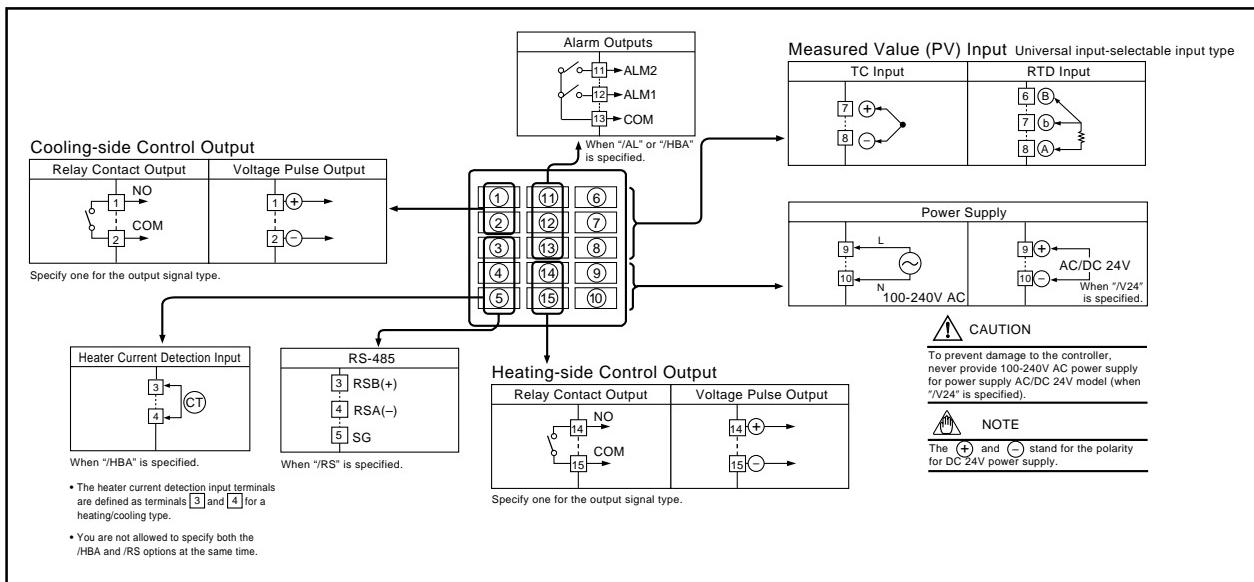
Use M3.5 screw-compatible crimp-on terminals with an insulating sleeve, as shown below.



■ UT130 Terminal Arrangement (Standard type)



■ UT130 Terminal Arrangement (Heating/cooling type)



7. KEY OPERATIONS

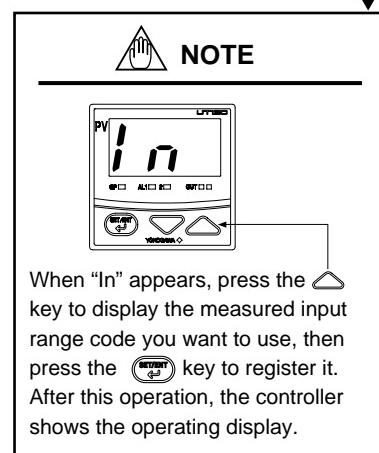


NOTE

At power-on, the temperature controller displays the operating display, but if the input range setting remains OFF, then “IN” appears. In this case, press the key to display the input range code you want to use, then press the key to register it. (Refer to the flowchart below.)

- (1) You can move between parameter setting displays using the key.
- (2) To change the set value,
 - (i) Change the display value with the or key (the period flashes).
 - (ii) Press the key to register the setting.
- (3) At the operating display, pressing the key for at least 3 seconds retrieves the operating parameter setting display.
- (4) At the operating parameter setting display, pressing the key for at least 3 seconds transfers back to the operating display. Registering the key-lock parameter LOC to “-1” retrieves the setup parameter setting display.
- (5) At the setup parameter setting display, pressing the key for at least 3 seconds transfers back to the operating display.

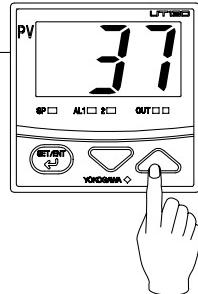
Note: If you cannot change the parameter setting value, check the key-lock parameter (LOC) setting.



● UT130 Measured Input Ranges

| Input type | Range (°C) | Range code (°F) | Range (°F) | Range code (°F) |
|--------------|-----------------|-----------------|---------------|-----------------|
| | Unspecified | OFF | | |
| Thermocouple | -199 to 999°C | 1 | -199 to 999°F | 31 |
| | 0 to 600°C | 2 | 32 to 999°F | 32 |
| | 0 to 400°C | 3 | 32 to 750°F | 33 |
| | -199 to 200°C | 4 | -199 to 400°F | 34 |
| J | -199 to 999°C | 5 | -199 to 999°F | 35 |
| T | -199 to 400°C | 6 | -199 to 750°F | 36 |
| E | -199 to 999°C | 7 | -199 to 999°F | 37 |
| L | -199 to 900°C | 12 | -199 to 999°F | 42 |
| U | -199 to 400°C | 13 | -199 to 750°F | 43 |
| RTD | -199 to 850°C | 15 | -199 to 999°F | 45 |
| | 0 to 400°C | 16 | 32 to 750°F | 46 |
| | -199 to 200°C | 17 | -199 to 400°F | 47 |
| | -19.9 to 99.9°C | 18 | -199 to 999°F | 48 |
| JPt100 | -199 to 500°C | 19 | | |

For example, to select thermocouple type E (°F), set the range code to 37.





CAUTION

To prevent electric shock, the controller should be mounted on the panel so that you do not accidentally touch the terminals when power is being applied.



IMPORTANT

The temperature controller is shipped with the parameters set at the factory-set defaults. Check the default values against the “Parameter Lists” in the following page (P.13, 14), and change the parameter settings that need to be changed.

This section explains how to set and register parameter values.

The procedure for changing SP (target setpoint) and A1 (alarm 1 setpoint) can be found on “Changing Target Setpoint (SP)” and “Changing Alarm 1 Setpoint (A1),” respectively. You can set the other parameters in the same way.

There are no setup displays for parameters specific to functions, such as the optional alarm output functions or heating/cooling control, if they were not selected at ordering.

The setting of some parameters (such as the control mode parameter CTL) determines whether the other parameters are displayed or not.

The flowchart (P.12) will help you understand how this works.

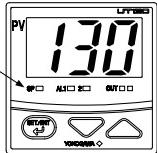
■ Changing Target Setpoint (SP)

The following instructions assume that the controller is already receiving power.

Step 1:

Confirm that the controller SP display lamp on shows the operating display during normal operation. (See note 1)

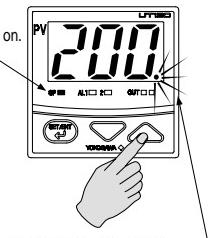
If the controller displays PV, press the  key once to display SP.



When PV is displayed on the operating display, a press of the  or  key switches to the SP display.

Step 2:

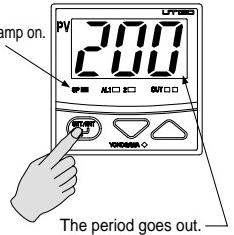
Press the  or  key to change the displayed SP value to the required value. In this example, SP is changed to 200°C.



The period flashes while the value is being changed.

Step 3:

Press the  key once to register the setting.



SP Display lamp on.

The period goes out.

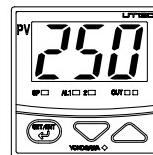
Note 1: The operating display shows either PV or SP. You can find out which data is displayed by the SP display lamp status.
 a. OFF: PV display of operating display
 b. ON: SP display of operating display
 c. Slow flashing: Parameter code is displayed.
 d. Quick flashing: Parameter value is being changed.

■ Changing Alarm 1 Setpoint (A1)

(This setpoint appears only if the /AL or /HBA option is specified.)

Step 1:

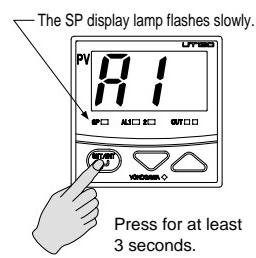
Confirm that the controller shows the operating display during normal operation. (See note 1)



Step 2:

To enter the operating parameter setting display, press the  key for at least 3 seconds.

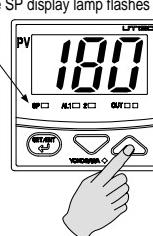
If your controller has the /AL or /HBA option, the display for the Alarm 1 setpoint (A1) appears. (If not, control mode (CTL) appears.)



The SP display lamp flashes slowly.
 Press for at least 3 seconds.

Step 3:

Press the  key once to display the current A1 value.



The SP display lamp flashes quickly.

Step 4:

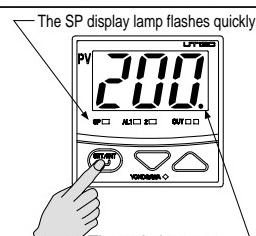
Press the  or  key to change the displayed A1 value. In this example, A1 is changed to 200°C.



The period flashes while the value is being changed.

Step 5:

Press the  key once to register the setting.

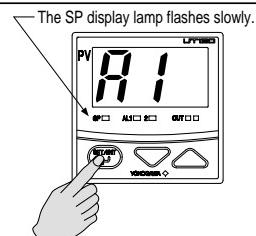


The SP display lamp flashes quickly.
 The period goes out.

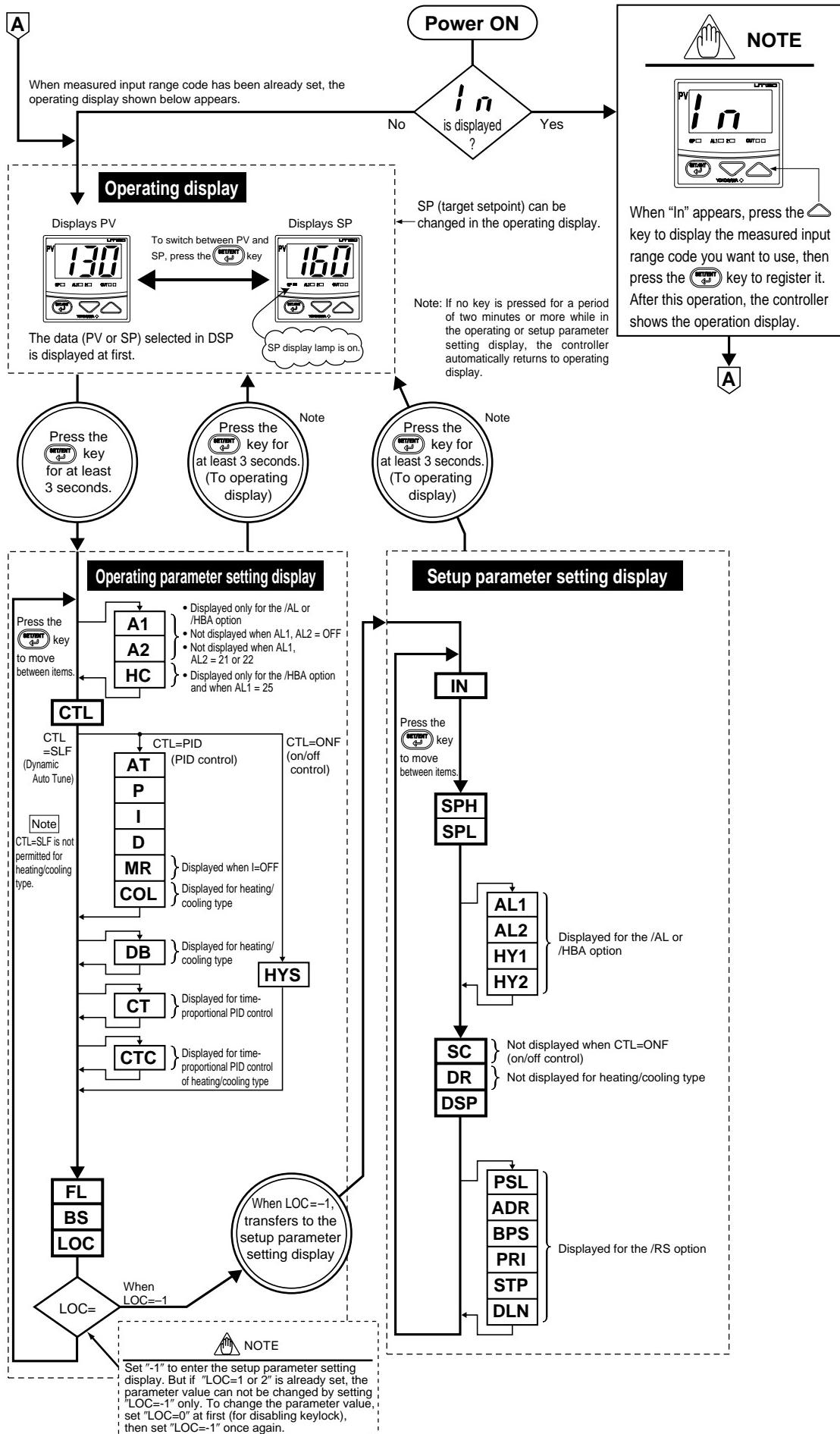
Step 6:

To return to the display at step 2, press the  key once again. Another press of the  key calls up the Alarm 2 setpoint (A2) display.

To return to the operating display, press the  key for at least 3 seconds.



The SP display lamp flashes slowly.



■ Parameter Lists

(1) Target Setpoint (SP)

Numbers in () are the parameter setpoints that apply when the communication function is used. Ex. OFF(0), ON(1)

| Code | Name | Setting range and unit | Default | User setting |
|--------------------|-----------------|--|---------|--------------|
| (SP value display) | Target setpoint | Minimum value (SPL) to maximum value (SPH) of target setpoint range Unit: °C/°F | SPL | |

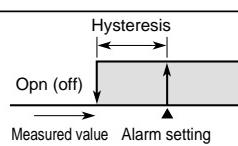
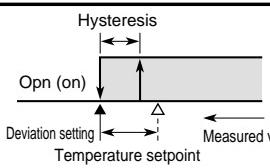
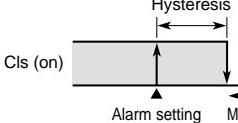
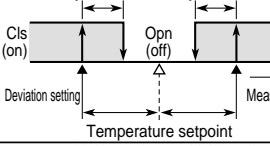
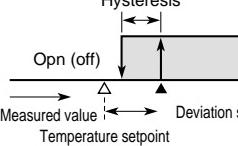
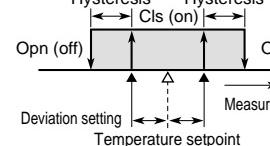
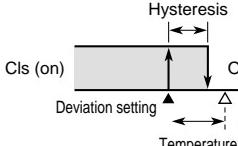
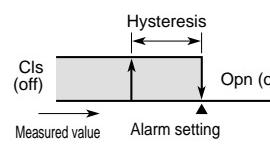
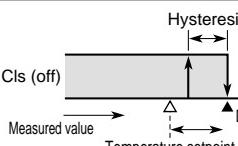
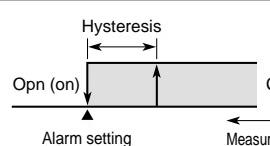
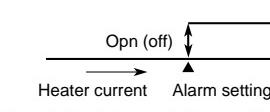
(2) Operating Parameters : Parameters changed rather frequently during operation.

| Code | Name | Setting range and unit | Default | User setting |
|----------------|---|--|---|--|
| A1 <i>A1</i> | Alarm 1 setpoint | <ul style="list-style-type: none"> ■ PV alarm Unit: °C/°F Setting range: minimum value to maximum value of measured input range ■ Deviation alarm Unit: °C/°F Setting range: -100 to 100% of the measured input range span | Max. value of measured input range (PV alarm) | |
| A2 <i>A2</i> | Alarm 2 setpoint | <ul style="list-style-type: none"> ■ Heater disconnection alarm Unit: A (ampere) Setting range: OFF(0), 1 to 80 (can be set for the alarm 1 setpoint only) | Min. value of measured input range (PV alarm) | |
| HC <i>HC</i> | Heater disconnection current measured value | “HC” is not a parameter to be set. The current value (0 to 80) of heater burnout detector is displayed. Unit: A (ampere) Settings: When the display value is ---, the heater current is not being measured. | | |
| CTL <i>CEL</i> | Control mode | ONF(0): On/off control PID(1): PID control SLF(2): Dynamic auto tune control (cannot be set for heating/cooling control) | | SLF(2) : standard type; PID(1) : heating/cooling type |
| AT <i>AT</i> | Auto-tuning | OFF(0): Stop auto-tuning(AT) ON(1): Start auto-tuning(AT) | | OFF(0) |
| P <i>P</i> | Proportional band | 1°C/°F to the temperature that corresponds to 100% of the measured input range span | | 5% of measured input range span |
| I <i>I</i> | Integral time | 1 to 999 seconds; OFF(0): no integral action | | 240 seconds |
| D <i>d</i> | Derivative time | 1 to 999 seconds; OFF(0): no derivative action | | 60 seconds |
| MR <i>mr</i> | Manual reset | -19.9 to 99.9 % : standard type -100 to 100 % : heating/cooling type | | 50.0% : standard type; 0.0% : heating/cooling type |
| COL <i>Col</i> | Cooling-side gain | 0.01 to 9.99 times | | 1.00 times |
| DB <i>db</i> | Deadband | <ul style="list-style-type: none"> ■ PID control Unit: °C/°F Setting range: -(proportional band setting) to +(proportional band setting) ■ On/off control Unit: °C/°F Setting range: -50 to +50% of measured input range span | | 3.0% of measured input range span |
| HYS <i>HYS</i> | Hysteresis for on/off control | 0°C/°F to the temperature that corresponds to 100% of the measured input range span | | 0.5% of measured input range span |
| CT <i>CT</i> | Control output cycle time | 1 to 240 seconds | | 30 seconds |
| CTC <i>CTC</i> | Cooling-side control output cycle time | 1 to 240 seconds | | 30 seconds |
| FL <i>FL</i> | PV input filter | OFF(0), 1 to 120 seconds | | OFF(0) |
| BS <i>BS</i> | PV input bias | -100 to 100% of measured input range span | | 0% of instrumented input range span |
| LOC <i>Loc</i> | Key lock | 0: No key lock 1: Prevents operations from being changed except for the changing of SP in the operating display 2: Prevents all parameter changing operations -1: Set “-1” to enter the setup parameter setting display. But if “LOC=1 or 2” is already set, the parameter value can not be changed by setting “LOC=-1” only. To change the parameter value, set “LOC=0” at first (for disabling keylock), then set “LOC=-1” once again. | | 0 |

(3) Setup Parameters : Parameters rarely changed in normal use after once having been set.

| Code | Name | Setting range and unit | Default | User setting |
|----------------|--|--|--|--------------|
| IN <i>In</i> | Measured input type | 1 to 7, 12, 13, 15 to 19, 31 to 37, 42, 43, 45 to 48 (See measured input range code list.) OFF(0): No input (If no input type is specified at the time of ordering, you must set the input type.) | OFF(0), or the input range code specified with order | |
| SPH <i>SPH</i> | Maximum value of target setpoint range | (SPH+1°C) to the maximum value of the measured input range; Unit: °C/F | Maximum value of measured input range | |
| SPL <i>SPL</i> | Minimum value of target setpoint range | Minimum value of measured input range to (SPH-1°C) Unit: °C/F | Minimum value of measured input range | |
| AL1 <i>AL1</i> | Alarm 1 type | OFF(0), 1 to 22 (See the alarm function list.) 25 (for the heater disconnection alarm /HBA option only) | 1 (PV high limit alarm) | |
| AL2 <i>AL2</i> | Alarm 2 type | OFF(0), 1 to 22 (See the alarm function list.) | 2 (PV low limit alarm) | |
| HY1 <i>HY1</i> | Alarm 1 hysteresis | 0 to 100% of measured input range span Unit: °C/F | 0.5% of measured input range span | |
| HY2 <i>HY2</i> | Alarm 2 hysteresis | | | |
| SC <i>SC</i> | SUPER function | ON(1): Uses the SUPER function OFF(0): Does not use SUPER function Note: Not displayed when on/off control | OFF(0) | |
| DR <i>dr</i> | Direct/reverse action | 0: Reverse action 1: Direct action Note: Not displayed for heating/cooling type | 0 | |
| DSP <i>dSP</i> | Priority of PV/SP display | 0: Displays PV 1: Displays target setpoint (SP) | 0 | |
| PSL <i>PSL</i> | Protocol selection | 0: PC-link communication 1: PC-link communication with sum check 2: Ladder communication 3: MODBUS in ASCII mode 4: MODBUS in RTU mode | 0 | |
| ADR <i>Adr</i> | Controller address | 1 to 99 However, the number of controllers that can be connected per host device is 31 at the maximum. | 1 | |
| BPS <i>bPS</i> | Baud rate | 2.4(0): 2400 bps 4.8(1): 4800 bps 9.6(2): 9600 bps | 9.6(2) | |
| PRI <i>Pr1</i> | Parity | NON(0): Disabled EVN(1): Even parity ODD(2): Odd parity | EVN(1) | |
| STP <i>STP</i> | Stop bit | 1 or 2 bits | 1 bit | |
| DLN <i>dln</i> | Data length | 7 or 8 bits • 8 bits when ladder, MODBUS (RTU) • 7 bits when MODBUS (ASCII) | 8 bits | |

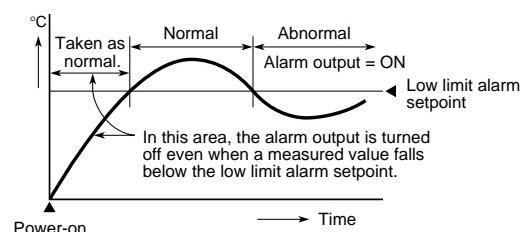
■ Alarm Function List

| Alarm type | Action | | Alarm type code | Alarm type | Action | | Alarm type code |
|--------------------------------------|--|---------------------------|------------------------|-------------------------------------|---|---------------------------|-------------------------|
| | Closed contact during alarm | Open contact during alarm | | | Closed contact during alarm | Open contact during alarm | |
| No alarm | | | OFF | | | | |
| PV high limit |  | | 1 11 (See note.) | De-energized on deviation low limit |  | | 6 16 (See note.) |
| PV low limit |  | | 2 12 (See note.) | Deviation high and low limit |  | | 7 17 (See note.) |
| Deviation high limit |  | | 3 13 (See note.) | Deviation within-high-and-low-limit |  | | 8 18 (See note.) |
| Deviation low limit |  | | 4 14 (See note.) | De-energized on PV high limit |  | | 9 19 (See note.) |
| De-energized on deviation high limit |  | | 5 15 (See note.) | De-energized on PV low limit |  | | 10 20 (See note.) |
| Fault diagnosis output | The contact is closed at input burnout. | | 21 | Heater disconnection alarm |  The controller starts measuring the current from the heater disconnection detector when 100 milliseconds have passed after turning on the output. | | 25 |
| FAIL output | The output contact is opened in the following events: <ul style="list-style-type: none">• Program error• ROM error• RAM error• power failure• A/D converter error• RJC error• EEPROM error | | 22 | | | | |

Note: The alarms numbered 1 to 10 have no waiting action, while alarms 11 to 20 have a waiting action.

The waiting action turns off the PV and deviation alarms that occur from the start of the control operation until a stable state is reached.

Waiting action



■ Description of Parameters

This section describes the parameter functions specific to the UT130 temperature controllers.
(The functions described in other sections of this manual and the general functions are not discussed.)

| Parameter | Function | Parameter | Function |
|----------------|---|----------------------|---|
| CTL | <p>Select one from the following:</p> <ul style="list-style-type: none"> a. Dynamic auto tune control (SLF) (See note) b. PID control (PID) c. On/off control(ONF) <p>Note: Dynamic auto tune control is not available for heating/cooling control.</p> <p>Read the section in Page 17 to find out more about dynamic auto tune control.</p> | PV input bias | <p>This function adds a bias value to the measured input value, and the result is used for display and control computation.</p> $\boxed{\text{PV value inside the controller}} = \boxed{\text{measured input value}} + \boxed{\text{PV bias}}$ |
| MR | You can set this parameter only for control without an integral action (when registered as CTL=PID and I=OFF). The controller outputs the manual reset (MR) value when PV=SP. For example, if you set MR=50%, the controller outputs (OUT) 50% when PV=SP. | BS | <p>This function is useful for carrying out fine adjustment when the PV value is within the required accuracy but it differs from the value obtained by other equipment.</p> |
| COL | <p>For heating/cooling control, you can set the ratio between the cooling-side output and heating-side output.</p> <p>For example, if you set COL=2.0 and the heating-side output is 10% at a certain deviation (SP-PV), then the cooling-side output will be 20% when the cooling-side also reaches that deviation.</p> | SPH, SPL | <p>Using the SPH and SPL parameters, you can limit the setting range of the target setpoint (SP) within the measured input range.</p> <p>This function prevents SP from being mistakenly set at too large or too small a value (beyond the setting range).</p> |
| DB | <p>You can only set a deadband for heating/cooling control. In a positive deadband, there are neither heating-side nor cooling-side outputs. In a negative deadband, there are both heating-side and cooling-side outputs, which overlap each other.</p> <p>1. When the deadband of a heating/cooling type is positive (Proportional band [P] control)</p> <p>2. When both the heating and cooling sides are under on-off control</p> | HY1, HY2 | <p>The alarms are output as relay outputs. Since a relay has a limited life, excessive on/off actions will shorten the life of the alarm. To prevent this, you can set a hysteresis band to prevent excessive on/off actions for both alarm 1 and alarm 2.</p> |
| HYS | <p>For on/off control (CTL=ONF), you can set a hysteresis around the on/off point (SP) to prevent chattering.</p> | SC | <p>The SUPER function is effective in the following cases:</p> <ol style="list-style-type: none"> An overshoot must be suppressed. The rise-up time needs to be shortened. The load often varies. SP is changed frequently. <p>Note 1: The SUPER function will not work when on/off control is selected, or I or D constants is set at OFF in PID control.</p> <p>Note 2: For some types of systems, the SUPER function may not be so useful. If this is the case, turn off the function.</p> |
| CT, CTC | <p>The cycle time is the period of on/off repetitions of a relay or voltage pulse output in time proportional PID control. The ratio of the ON time to the cycle time is proportional to the control output value.</p> | DSP | <p>Since the UT130 controller has a single data indicator, you can give display priority to either PV or SP. The data which has the priority will be displayed on the data indicator upon power-on or when the operation display is resumed from a parameter setting display using the key (by pressing for at least 3 seconds).</p> <p>Displays PV</p> <p>Displays SP</p> <p>SP display lamp is on.</p> <p>To switch the display between PV and SP, press the key.</p> |
| FL | <p>This function should be used when the PV display value may fluctuate greatly, for example, when the measured input signal contains noise. The filter is of the first-order lag type, and FL sets the time constant. If a larger time constant is set, the filter can remove more noise.</p> | | |

■ What is Dynamic Auto Tune Control?

Dynamic auto tune control is one of the features offered by the temperature controller.

When the controller is turned on or the process variable (PV) starts “hunting”, this mode of control monitors the behavior of the PV and/or OUT (control output value) to automatically determine the optimum PID constants. This means that the PID constants may be changed automatically. If this is not desirable for your system, operate the controller in the normal “PID control”.

If you want to automatically determine the PID constants at the initial startup of the controller, first define the target setpoint variable (SP) and then turn the controller off once and then back on again. Do not use dynamic auto tune control for a system where there is interference or continual disturbances.



IMPORTANT

To use dynamic auto tune control,

- (1) be sure to turn on the final control element, such as a heater, before starting the control, and
- (2) make sure the controlled loop is a closed loop.

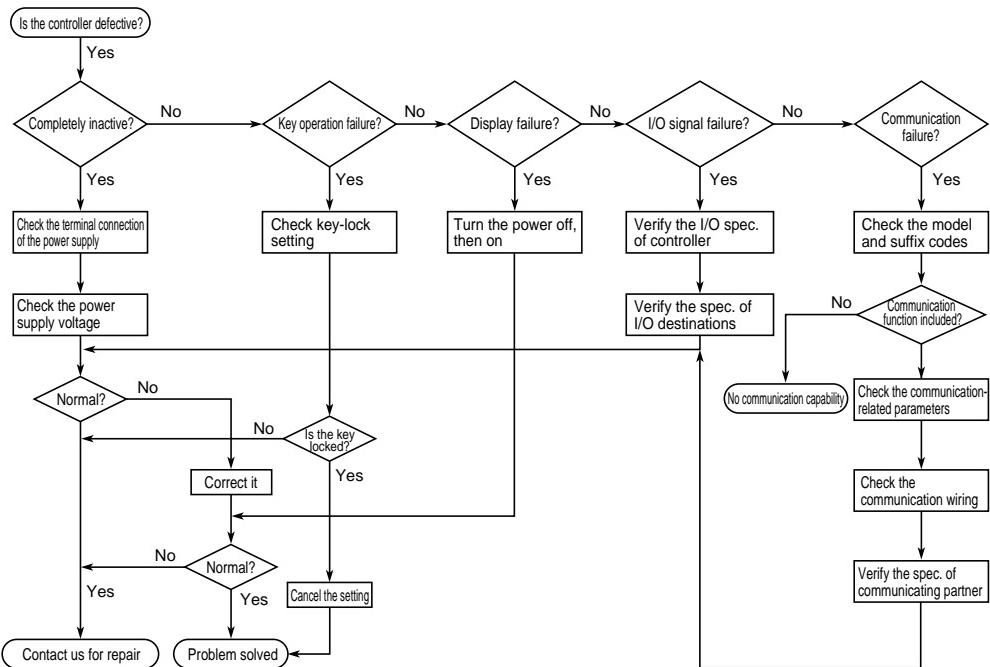
If you do not follow these precautions, improper PID constants may be written into the controller. If this occurs, carry out the following:

- Set the parameter CTL at PID.
- Set the PID constants at the factory-set defaults ($P = (\text{upper range-limit} - \text{lower range-limit}) \times 5\%$; $I = 240 \text{ sec.}$; and $D = 60 \text{ sec.}$)
- Set the parameter CTL at SLF.

If the control still doesn't work properly, stop using the dynamic auto tune control function. Change the parameter CTL setting to PID and execute auto-tuning to obtain the PID constants.

8. TROUBLESHOOTING

In the event of an abnormality, perform the following checks as outlined by the flowchart.



■ Error Display during Operation

(1) If the controller displays one of the following, carry out the appropriate remedy for the particular error.

| Display | Error content | Remedy |
|----------------------------------|---|---|
| P.Er P.Er | The parameter is abnormal | Check the settings of all the parameters and set them at their proper values. |
| B.o B.o | Input burnout | Check the sensor wiring and correct it. |
| 000 000 | PV over-scale (PV exceeds its effective range.) | Check the input type and range settings and correct them. |
| UUU UUU | PV under-scale (PV falls below its effective range.) | |
| Flashing period on PV display | Communication failure (for /RS option only) | Press any key to stop the flashing. |

(2) The controller needs to be repaired if any of the indications in the table below appear.

In these cases, do not try to repair the controller yourself. Order a new controller or contact us for repair.

| Display | Error content | Display | Error content |
|--------------------------------|----------------------|-----------------------------------|--|
| Unknown (at power-on) | CPU failure | Flashing "Err" (at power-on) | RAM or ROM failure |
| All extinguished (at power-on) | Power source failure | Flashing "Err" (during operation) | A/D converter failure, RJC failure, or EEPROM failure |
| "Err" (at power-on) | Calibration abnormal | | |

■ When Power Failure Occurred during Operation

- Momentary power failures of less than 20ms (or less than 1ms when "/V24" is specified), have no effect on the controller operation (i.e., normal operation continues).
- For power failures longer than 20ms (or longer than 1ms when "/V24" is specified), however the status will be as follows.
(The controller action at power recovery is the same as at power-on.)
 - Alarm action: Continues (but alarms with a waiting action enter the waiting state once)
 - Setting parameters : Maintained
 - Auto-tuning: Canceled

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△NOTICE

- Before using the product, read the instruction manual carefully to ensure proper operation.

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